



ASAC 2019

Report IFAC ASEAN School of Advanced Control

From Fundamental Theory to Robust and Networked Control Technologies towards Smart Cities

January 15-16, 2019 Chulalongkorn University, Bangkok, Thailand

Supported IFAC NMOs: Singapore and Malesia NMOs

Supported in part by

Department of Electrical Engineering, Chulalongkorn University, Thailand JICA (Japan International Cooperation Agency) AUN/SEED-Net Program (ASEAN University Network /South East Asia Engineering Education Development Network)

Jointly with

ICA-SYMP 2019 (International Symposium on Instrumentation, Control, Artificial Intelligence, and Robotics) held on January 16-18, 2019, which was organized by Electrical Engineering/Electronics, Computer, elecommunications and Information Technology (ECTI), Thailand

Final Program

January 15 (Tue), 2019

0.20 0.40	On arrive Cassian
8.20 - 8:40 8:40 - 9:50	Opening Session
6.40 - 9.30	Lecture T1 (Prof. Shinji Hara) Introduction to Control Theory and Technology towards Smart Cities (1)
	From Classical and Optimal Control to Robust Control
	Coffee break>
10:10 - 11:20	Lecture T2 (Prof. Mi-Ching Tsai)
10.10 11.20	Robust Control Synthesis with Industrial Applications (1)
	Robust Control and H infinity Control Synthesis
11:20 - 12:30	Lecture T3 (Prof. Mi-Ching Tsai)
11.20 12.00	Robust Control Synthesis with Industrial Applications (2)
	Industrial Applications
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14:00 - 15:10	Lecture T4 (Shinji Hara)
	Introduction to Control Theory and Technology towards Smart Cities (2)
	From Robust Control to Decentralized Control for Multi-agent Systems
	<coffee break=""></coffee>
15:30 - 16:30	Online lecture T5 (Prof. Su Rong)
	Smart City Applications (1)
	Distributed Adap.ve Urban Traffic Signal Control based on V2X
	Information Infrastructure
16:30 - 17:30	Lecture T6 (Prof. Shinji Hara)
	Smart City Applications (2)
	Glocal Control for Energy Network Systems
18:00 - 20:00	Reception
	January 16 (Wed), 2019
8:40 - 10:10	Lecture W1 (Prof. Hyungbo Shim)
	Networked Control for Multi-agent Systems (1)
	Analysis and Synthesis
	<coffee break=""></coffee>
10:30 - 12:00	Lecture W2 (Prof. Itthisek Nilkhamhang)
	Networked Control for Multi-agent Systems (2)
42.00 42.25	Applications to Smart Manufacturing
12:00 - 12:30	Short Presentations for Poster Papers
12.50 45.20	<lunch break=""></lunch>
13:50 - 15:30	Poster Session
15:45 - 16:00	Closing Session

Poster Session Program

Development of Computer Vision-Based Movement Controlling in Mecanum Wheel Robotic Car	MIN YAN NAING, Yangon Technological University, Myanmar
Aircraft at Height Angles of Attack with Sliding Mode Control	Nurhana Binti MOHMAD ROUYAN, Universiti Putra Malaysia, Malaysia
Design and Implementation Fast Response System Monitoring Server Using Simple Network Management Protocol (SNMP)	ISTAS PRATOMO, Institut Teknologi Sepuluh Nopember, Indonesia
Solving Travelling Salesman Problem by using Hybrid Bees Algorithm	Liengheng YANG, Universiti Putra Malaysia, Malaysia
Visual Odometry for GPS Denied Navigation Tunnels	Matthew Rongfa NG, Singapore University of Technology and Design, Singapore
Real-Time Self-Driving Car Navigation using Deep Neural Network	Minh Thien DUONG, Ho Chi Minh City University of Technology and Education, Vietnam
Experiment on Real-Time Image Processing in the Controlling of Mecanum Wheel Robotic Car	AUNG SAN OO, Yangon Technological University, Myanmar
Real-time Night Time Driver Drowsiness Detection using Deep Neural Network	Truong-Dong DO, Ho Chi Minh City University of Technology and Education, Vietnam
Design and Implementation of Fixed-Wing Unmanned Aerial Vehicle (Mathematical modeling and Stability Analysis)	Hteik Tin Cho NYUNT, Yangon Technological University, Myanmar
Appliance Classification Method Based On K-Nearest Neighbors for Home Energy Management System	Thanh-Dat NGUYEN, Ho Chi Minh City University of Technology and Education, Vietnam
Design and Implementation of Fixed-Wing Unmanned Aerial Vehicle (Autopilot)	Thanda WIN, Yangon Technological University, Myanmar
Immersive Virtual Reality Application of Engine Assembly and Disassembly to enhance learning performance	Lai Lai WIN, Universiti Putra Malaysia, Malaysia
	Aircraft at Height Angles of Attack with Sliding Mode Control Design and Implementation Fast Response System Monitoring Server Using Simple Network Management Protocol (SNMP) Solving Travelling Salesman Problem by using Hybrid Bees Algorithm Visual Odometry for GPS Denied Navigation Tunnels Real-Time Self-Driving Car Navigation using Deep Neural Network Experiment on Real-Time Image Processing in the Controlling of Mecanum Wheel Robotic Car Real-time Night Time Driver Drowsiness Detection using Deep Neural Network Design and Implementation of Fixed-Wing Unmanned Aerial Vehicle (Mathematical modeling and Stability Analysis) Appliance Classification Method Based On K-Nearest Neighbors for Home Energy Management System Design and Implementation of Fixed-Wing Unmanned Aerial Vehicle (Autopilot) Immersive Virtual Reality Application of Engine Assembly and Disassembly to enhance learning



Group Photo after the Morning Session of the First Day



Group Photo after the Closing Ceremony of the Second Day (Invited Speakers, Operating Committee Members, and Poster Session Speakers)

Summary of Participants

5 Invited Speakers

Shinji Hara (Chuo Univ., Japan)

Mi-Ching Tsai (National Cheng Kung Univ., Taiwan)

Hyungbo Shim (Seoul National Univ., Korea)

Itthisek Nilkhamhang (Thammasat Univ., Thailand)

Su Rong (Nanyang Technological Univ., Singapore)

5 Operating Committee Members (all from Thailand)

12 Participants from ASEAN Countries supported by IFAC Foundation All of them are Poster Session Presenters

(see the Poster Session Program)

37 Participants from Thailand

(pre-registration without support by IFAC Foundation)

Several other people who originally registered to ICA-SYMP2019

Summary of Expense

- Total amount of expenses: 196,690 THB (app. = 6,220 USD, 5,470 EUR)
 - a. 12 oversees participants (Poster Session presenters): 113,319 THB airplane tickets: 98,319 THB, accommodation (CU iHouse): 15,000 THB
 - b. accommodation (Hotel) for 3 overseas invited lecturers: 29,700 THB
 - c. welcome reception, lunch and coffee break: 47,852 THB
 - d. others (printing and poster session): 5,819 THB

Remarks:

The total amount of expenses is less than the half of the budget. The reasons are

- (i) The number of the participants supported is the three quarter of the original plan, and the costs of air tickets and accommodations were cheaper than expected.
- (ii) The number of the overseas speakers is also the three quarter of the original plan, because Su Rong gave his lecture by a video.
- (iii) One of the receptions was jointly organized with ICA-SYMP2019, which covered all the costs for the reception.

Evaluation

- Evaluation on the school:
- (i) Number of participants: We have expected in total 16, two people from each ASEAN countries except Thailand. However, unfortunately, there was no applications from Cambodia, Laos, and Philippines, and hence the total is reduced to twelve. The number of participants from Thailand is 37, which is nearly equal to our expectation. We also had some extra participants, who registered to ICA-SYMP2019. This is one of the benefits of the idea of holding the school with ICA-SYMP2019.
- (ii) Program of the school: Most of the participants had positive comments for the combination of fundamental part and advanced part for lectures. The poster session was very successful. It was a good occasion for the presenters to have discussions with the invited speakers, which we can expect the improvement of their researches. It also provided a chance of collaborations among them.
 - Benefits for future:
- (i) Collaborations in Asia: This school is start of collaborations among not only ASEAN countries but also all in Asia. More collaborations in Asia through several activities by ACA (Asian Control Association) could be expected.
- (ii) IFAC: Higher level of control education and research activities, which might yield increase of paper submissions of IFAC2023 in Yokohama, Japan. Thailand recently decided to become a member of IFAC. Note that one of the main reasons for starting the ICA-SYMP is to get the money for paying the membership fee. We may expect that we have more IFAC members from Asia through this kind of events for supporting their activities.

Operating Committee Members

Chair Shinji Hara (Japan)

Coordinator David Banjerdpongchai (Thailand)
Secretary Sungwan Boksuwan (Thailand)
Registration Napasool Wongvanich (Thailand)

Local Arrangement Jitkomut Songsiri (Thailand)

Publication Supachai Vorapojpisut (Thailand)